# **Transition Edge Sensors**

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#### Literature/Acknowledgement

- Acknowledgement to Christian Enns and Dan McCammon for making available lecture material on TES-micro-calorimeters
- Acknowledgement to Marcel Bruijn and Bob Dirks for making sheets on the production process and on device characterization available
- For literature please read:
  - Transition-Edge Sensor by Kent Irwin and Gene Hilton in Cryogenic Particle Detectors, Topics in Appl. Physics, Vol 99 Editor: Christian Enns, Springer Verlag (2005)
  - Proceedings of Low Temperature Detector (LTD) conferences and references in there

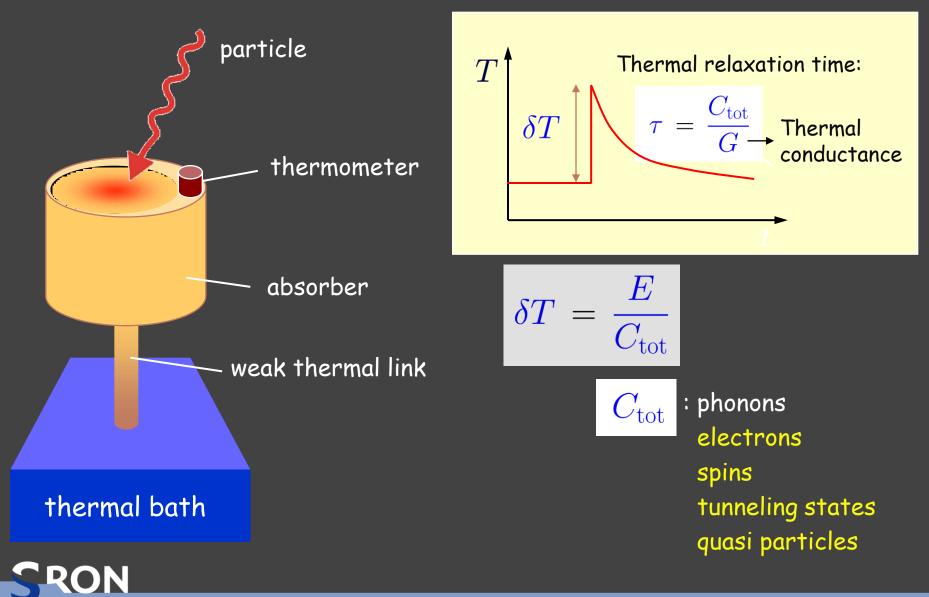


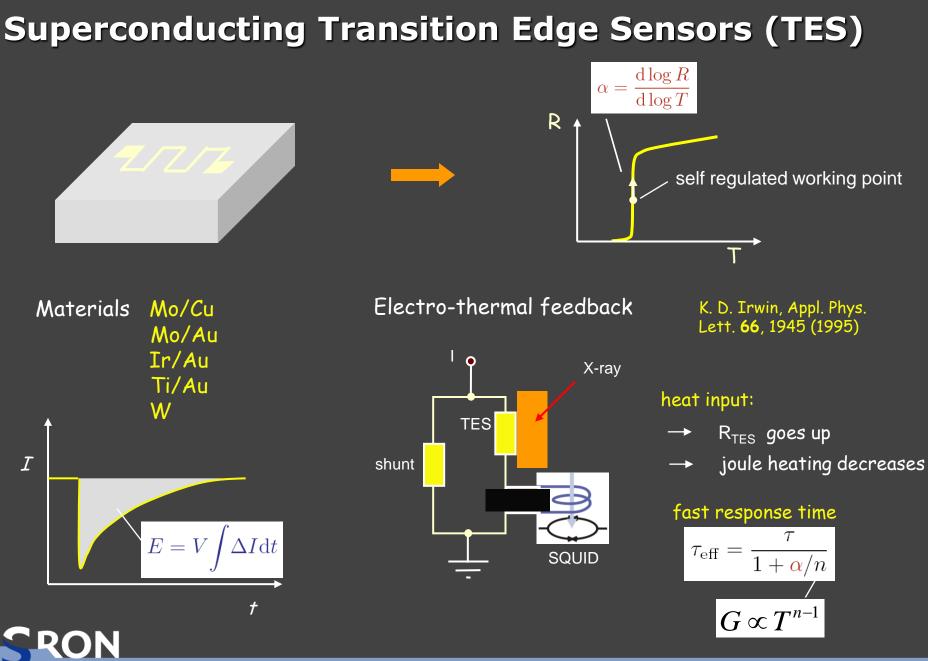
### **Content TES physics**

- 1) Schematic of Calorimeter Principle
- 2) Electro-thermal feedback
- 3) Basic Pixel Design
  - 1) Heat Capacity
  - 2) Heat Conductance
  - 3) TES-bolometer
- 4) Differential equations
  - 1) Linearization
  - 2) Matrix notation in frequency domain
  - 3) Responsivity
  - 4) Noise
  - 5) Complex impedance
- 5) Energy resolution
  - 1) Time domain
  - 2) Frequency domain
- 6) Pixel characterization (example)



#### **Calorimeter Principle**

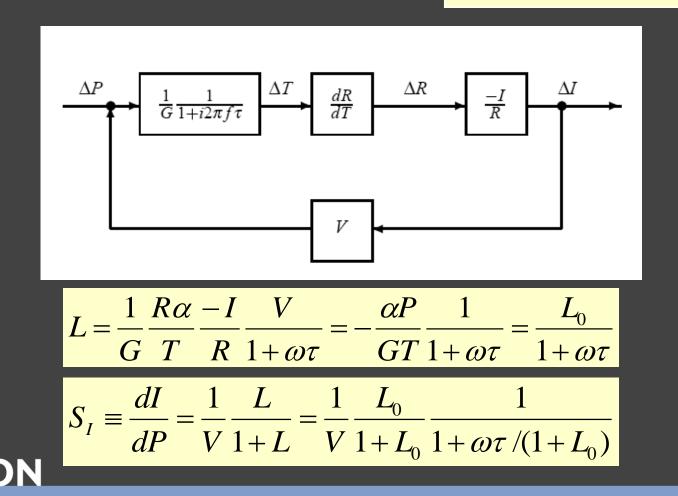




# Electro-thermal Feedback

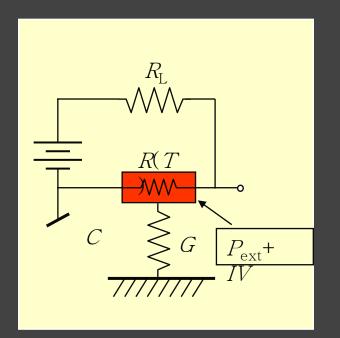
$$S = \frac{V_{out}}{V_{in}} = \frac{1}{\beta} \frac{A\beta}{1 + A\beta}$$

$$\overrightarrow{\beta}$$



### **Open loop gain**

 $L_{0} = \alpha P / GT$   $P = K(T^{n} - T_{0}^{n})$   $G = nKT^{n-1}$   $L_{0} = \frac{\alpha}{n} [1 - \left(\frac{T}{T_{0}}\right)^{n}] \approx \alpha / n$ 



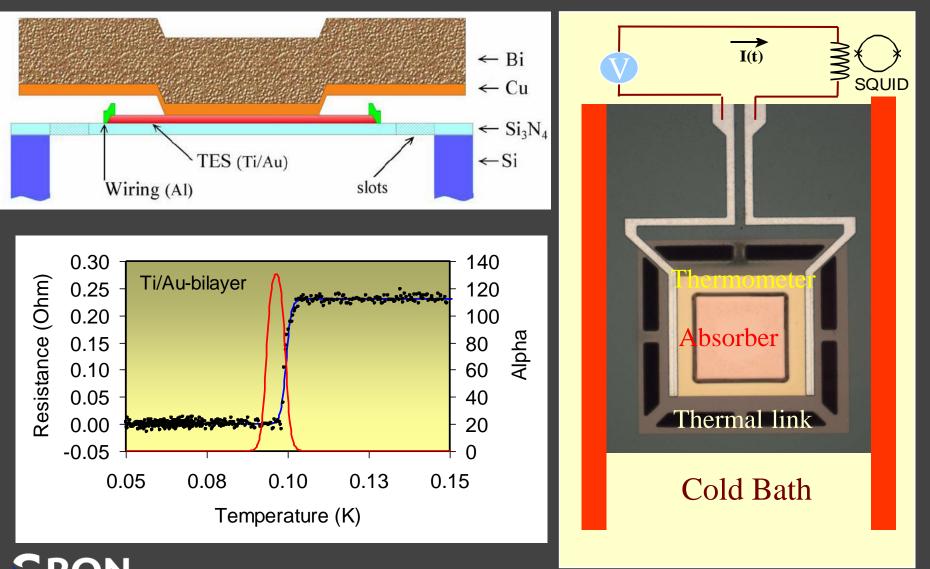
$$F_L = \frac{R - R_L}{R + R_L}$$

Influence load resistor  $L = L.F_{L}$ 



#### **TES-based Micro-Calorimeter**

#### **BASIC PIXEL DESIGN**





# **Typical Design parameters**

- Heat Capacity
  - Electronic heat capacity  $C = \gamma T V$  ( $\gamma$  the Sommerfeld parameter)
  - Phonon heat capacity C = A.T<sup>3</sup>.V
  - For T < 1 K the C of normal metals is dominated by the electronic heat capacity (not for Bi)</li>

Typical heat capacity of one pixel at T = 100 mK:

- TES 150 x 150  $\mu$ m of 25nm Ti ( $\gamma$  = 315) and 50 nm Au ( $\gamma$  = 71). An area of 100 x 100  $\mu$ m<sup>2</sup> under stem is normal (N), the S-rim is biased at R/R<sub>n</sub> = 0.2. C superconductor phase = 2.43x that of normal phase
- Cu-conductor 250 x 250 μm of 0.3 μm (γ = 97)
- Bi-absorber 250 x 250  $\mu$ m of 3  $\mu$ m ( $\gamma$  = 3.9 ??)
- SiN-membrane (220 x 180 x 1 μm)

Total heat capacity/pixel

 $C_{\text{TES}} = 7 \ 10^{-14} \ \text{J/K}$   $C_{\text{cu}} = 1.8 \ 10^{-13} \ \text{J/K}$   $C_{\text{BI}} = 7.3 \ 10^{-14} \ \text{J/K}$   $C_{\text{SIN}} \approx 1 \ 10^{-13} \ \text{J/K}$ 

 $C_{totaal} = 0.42 \text{ pJ/K}$ 

 $E_{MAX} = C.\delta T \approx CT/a$  For a  $\approx T/\delta T \approx 100$  we get  $E_{MAX} \approx 2.6$  keV



### **Typical Design Parameters for heat transport**

- Design of Heat Conductance value
  - Given typical electro-thermal feedback loop gains of 20x (eff. a = 100)
  - Design a pixel with an effective time constant of 100  $\mu s$
  - $\rightarrow$  C/G = 2 ms or  $\rightarrow$  G  $\approx$  2.5 10<sup>-10</sup> W/K
- Heat transport
  - Generation of heat in electrical system of TES/absorber
  - Heat transport to bath by phonon's in membrane:

1) e-ph coupling in TES/absorber  $G_{e-ph} = n.\Sigma.VT^{n-1}$  with n = 5 and  $\Sigma = 2 \ 10^9 \text{ W/K}^5\text{m}^3$ . So  $\rightarrow G_{e-ph} \approx 2 \ 10^{-7} \text{ W/K}$ 

- 2) Kapitza coupling to membrane  $G_{kapitza} = n.a_K.A.T^{n-1}$  with n = 4. Typically  $a_K = 125 \text{ W/K}^4\text{m}^2$ . So  $G_{kapitza} = 1.12 \text{ 10}^{-8} \text{ W/K}$
- 3) Radiative phonon transport (Hoevers et al. Appl.Phys.Lett 86, 251903 (2005))  $G_{memb} = \xi . \sigma_B . n . A_{ph} . T^{n-1} W/K^3m^2$  with n = 4. Typically  $\xi = 0.78$ . The Stefan-Boltzmann constant for phonon transport equals  $\sigma_B = 157 W/K^4m^2$ . So for  $A_{ph} = 4 \times 150 \times 1 \ \mu m^2 \rightarrow G_{memb} = 2.9 \ 10^{-10} W/K$ Reduction of this value is possible by structuring the SiN-membrane. Typical P  $\approx$  TG/n = 6 pW



#### **TES-Bolometer characteristics**

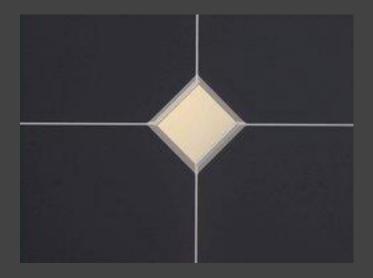
 $P = K(T^n - T^n_{bath})$ • NEP and Dynamic Range  $NEP = \sqrt{4\gamma kT^2 G} \cong \sqrt{4\gamma nkTP} \quad \frac{\Delta I}{i_n} = \frac{(1-r)P}{NEP} = (1-r)\sqrt{\frac{P}{4\gamma nkT}}$  $d^{-10}$  $10^{6} \cdot 10^{6}$ Dyn. Range (Hz) NEP (W/rootHz)  $1 \cdot 10^{5}$  $1.10^{-18}$ 0.8 P(k)NEP(k) NEP(k)  $1.10^{-19}$  $1 \cdot 10^{4}$  $10^{3}_{1.10^{3}}$  $-9-10^{-20}$  $1.10^{-15}$  $1.10^{-14}$  $1.10^{-13}$  $1.10^{-12}$  $1.10^{-13}$  $1.10^{-15}$  $1.10^{-12}$  $1.10^{-14}$  $10^{-15}$ P(k) $10^{-12}$  $10^{-15}$  $10^{-12}$ P(k)BIAS Power (W) BIAS Power (W)

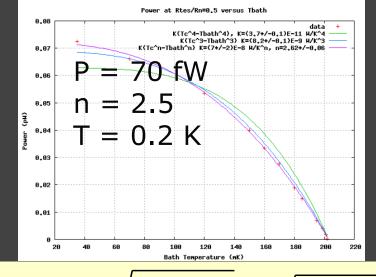
#### • Time constant

$$\tau_{e\!f\!f} = \!\frac{C}{G} \frac{1}{1 + L_0} \cong \frac{CT}{\alpha P}$$

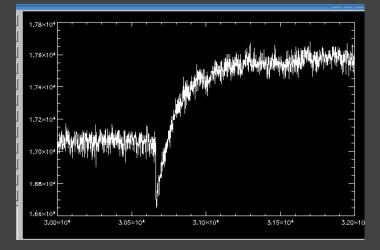
C/G ≈ 4 ms NEP= 10<sup>-18</sup> W/√Hz

#### Low NEP TES-bolometer for SAFARI (SPICA)





 $NEP = \sqrt{4kT^2}P \approx \sqrt{4kTP}$ 



 $T_{C} = 200 \text{ mK}$ 100 x 100 µm TES 4 legs of 5 µm and Nex 1.8 mm

Next steps:

T  $\rightarrow$  100 mK Leg width  $\rightarrow$  2  $\mu$ m

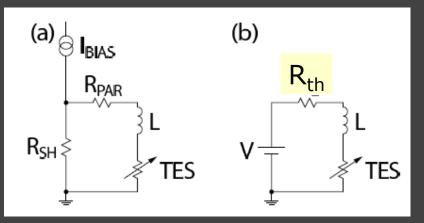
Measured P = 70 fW NEP =  $10^{-18}$  W/ $\sqrt{Hz}$ T<sub>eff</sub> = 0.2 ms

# **Differential Equations**

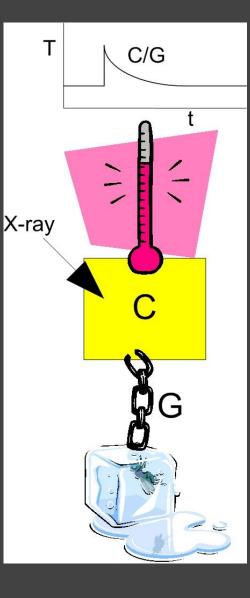
• Thermal differential equation

$$C\frac{dT}{dt} + P_{bath} + I_0 V_{Johnson} = P_{Joule} + P$$

• Electrical differential equation



$$L\frac{dI}{dT} + I.R_{th} + I.R(T,I) = V + V_{Johnson} + V_{Noise}$$





#### Linearizations (small signal approximation)

$$P_{bath} = K(T^{n} - T_{bath}^{n})$$
$$G \equiv \frac{dP_{bath}}{dT} = nKT^{n-1}$$
$$P_{bath} \approx P_{bath0} + G.\Delta T$$

- n = 5 electron-phonon transport
- n = 4 Kapitza boundary
- n = 3 Phonon transport

$$R(T,I) \approx R_0 + \alpha_I \cdot \frac{R_0}{I_0} \cdot \Delta I + \alpha_T \cdot \frac{R_0}{T_0} \Delta T$$

Resistance does also depend on I through action of B-field

$$P_{Joule} = I^2 \cdot R = P_{J0} + 2 \cdot I_0 \cdot R_0 \cdot \Delta I + \alpha_I \cdot \frac{P_{J0}}{I_0} \cdot \Delta I + \alpha_T \cdot \frac{P_{J0}}{T_0} \cdot \Delta T$$



#### **Matrix solution**

$$\begin{bmatrix} \Delta I \\ \Delta T \end{bmatrix} \begin{bmatrix} i\omega L + R_{th} + R_0(1 + \alpha_I) & \frac{R_0 I_0}{T_0} \alpha_T \\ -R_0 I_0(2 + \alpha_I) & i\omega C + G - \frac{P_{J0} \alpha_T}{T_0} \end{bmatrix}^{-1} = \begin{bmatrix} V_{Johnson} + V_{noise} \\ -I_0 V_{Johnson} + P \end{bmatrix}$$

#### Responsivity

$$S_{I} \equiv \Delta I / P = M_{0,1}^{-1}$$

$$S_{I} = -\frac{1}{I_{0}R_{0}} \left( (1 + \frac{1 + \alpha_{I}}{L_{0}})(1 + i\omega\tau_{fall}) + \frac{R_{th} + i\omega L}{R_{0}} (1 - \frac{1}{L_{0}})(-1 + i\omega\tau_{eff}) \right)^{-1}$$
With  $L_{0} = \frac{\alpha P}{GT}$  the electro-thermal loop gain and  $\tau_{eff} = \tau_{0} / L_{0} - 1$ 

$$C = 1$$

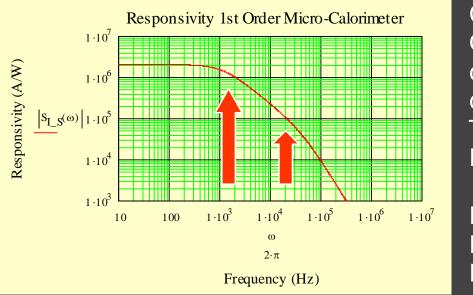
This equation shows one pole (fall time) at :  $\frac{\tau}{\tau}$ 

$$_{fall} = \frac{C}{G} \frac{1}{1 + L_0 / (1 + \alpha_I)}$$

And a 2<sup>nd</sup> pole (rise time) at :

$$\tau_{el} = L/(R_{th} + R_0(1 + \alpha_I))$$

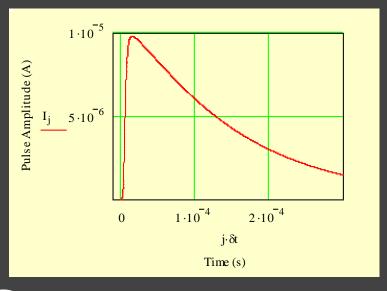
### **Typical Micro-calorimeter Responsivity**



C = 0.5 pJ/K  
G = 0.35 nW/K (P = 9 pW)  

$$a_T = 100$$
  
 $a^I = 1$   
T = 0.1 K  
 $L_0 \rightarrow 25$ 

 $\begin{array}{l} \mathsf{R}_0 = 40 \text{ mOhm} \\ \mathsf{R}_{th} = 10.6 \text{ mOhm} \\ \mathsf{L} = 600 \text{ nH} \end{array}$ 



1st pole 1.5 kHz/110  $\mu$ s (signal fall time)

2nd pole 24 kHz/6.7 µs (signal rise time)

#### **Matrix solution**

$$\begin{bmatrix} \Delta I \\ \Delta T \end{bmatrix} \begin{bmatrix} i\omega L + R_{th} + R_0(1 + \alpha_I) & \frac{R_0 I_0}{T_0} \alpha_T \\ -R_0 I_0(2 + \alpha_I) & i\omega C + G - \frac{P_{J0}\alpha_T}{T_0} \end{bmatrix}^{-1} = \begin{bmatrix} V_{Johnson} + V_{noise} \\ -I_0 V_{Johnson} + P \end{bmatrix}$$

#### Thermal fluctuation noise

$$I_{Phonon} = P_{phonon} M_{INV}(0,1)$$

#### Johnson Noise

$$I_{Johnson} = V_{Johnson} [M_{INV}(0,0) - I_0 M_{INV}(0,1)]$$

#### Shunt noise

$$I_{shunt} = V_{noise} M_{INV}(0,0)$$

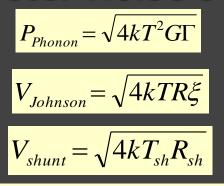


## Micro-Calorimeter Noise sources

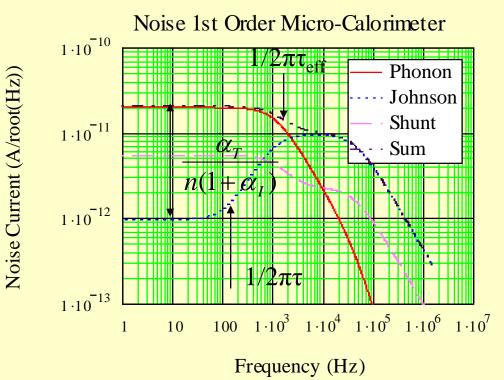
1) Phonon Noise

2) Johnson Noise

3) Shunt noise



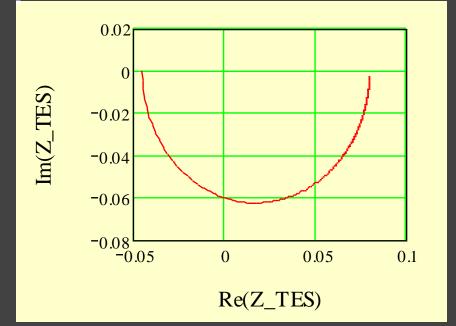
in W/ $\sqrt{Hz}$  with  $\Gamma \approx 0.5$ in V/ $\sqrt{Hz}$  with  $\xi = 1 + 2\alpha_I$ in V/ $\sqrt{Hz}$ 



 $\begin{array}{l} {\sf R}_{sh} = \ 10.6 \ m\Omega \\ {\sf T}_{sh} = \ 60 \ mK \end{array}$ 

#### **Complex Impedance**

$$Z_{TES} = M_{INV}^{-1}(0,0) - (R_{th} + i\omega L)$$

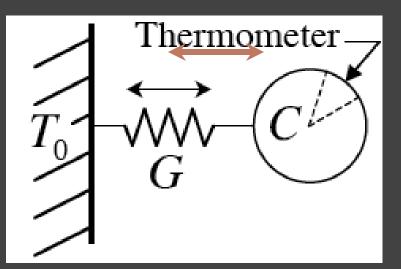


$$Z(0) = -R_0 \frac{1 + \alpha_I + L_0}{L_0 - 1}$$
$$Z(\infty) = R_0 (1 + \alpha_I)$$
$$\tau_{eff} = \frac{\tau_0}{L_0 - 1}$$

The effective time constant equals  $1/\omega$  for the minimum imaginary number



# **Energy Resolution**



Random transport of energy between heat sink and detector over thermal link G produces fluctuations in the energy content of C. The magnitude of these can easily be calculated from the fundamental assumption and definitions of statistical mechanics:

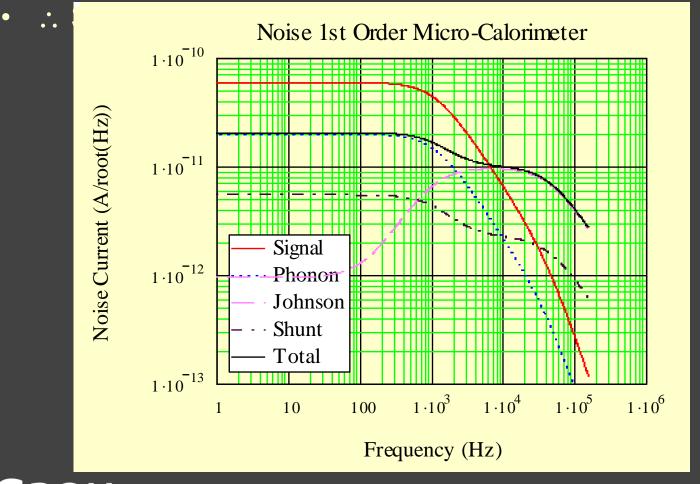
$$\sigma_E^2 = \mathrm{k} \, T^2 C$$

"Thermodynamic Fluctuation Noise" (TFN)

Can think of as Poisson fluctuations in number of energy carriers in *C* with mean  $C_N \approx \frac{CT}{kT}$ ,  $\Delta E_{rms} = \sqrt{N} \cdot (kT) = \sqrt{kT^2C}$ .) Not a limit on resolution, but sets the

# **Energy Resolution**

- Noise in different frequency bins uncorrelated
- Each frequency bin gives independent estimate of signal amplitude



### **Energy Resolution in time domain**

$$\Delta E = 2\sqrt{2 \ln 2} NEP(0) \sqrt{\tau^*}$$
<sup>1</sup>  
n  
$$NEP(0) = \sqrt{4kT^2G\Gamma}$$
with  $\Gamma =$ 

 $1/2\pi\tau^*$  frequency where Johnson noise and TFN cross each other

 $\mathcal{T}^{*} = \frac{C}{G} \frac{1}{r}$   $\mathcal{T}^{*} = \frac{C}{G} \frac{1}{r}$   $\mathcal{T}^{*} = \frac{C}{G} \frac{1}{r}$   $1/r = \sqrt{\frac{4kT/R}{4kT^{2}G\Gamma}} \frac{1}{L_{eff}} V \frac{1+L_{eff}}{L_{eff}} \approx \frac{1+\alpha_{I}}{\alpha_{T}} \sqrt{\frac{n(1+2\alpha_{I})}{[1+\left(\frac{T_{0}}{T}\right)^{n}].\Gamma}}$ Frequency

0.5

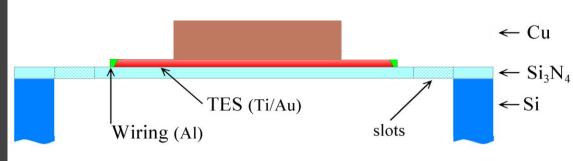
For C = 0.5 pJ/K, n = 3,  $a_T = 100$ ,  $a_I = 1$ , and T = 0.1 K we get:  $\Delta E = 1.64 \text{ eV}$ 



### **Detector Characterization**

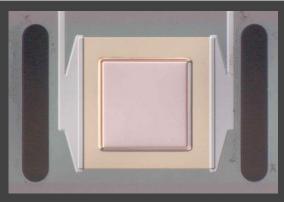
- Full Characterization includes:
- RT measurements
- IV, f(T<sub>bath</sub>, magnetic field)
- Complex impedance
- Noise
- Baseline + X-ray energy resolution

#### Example: central Cu absorber



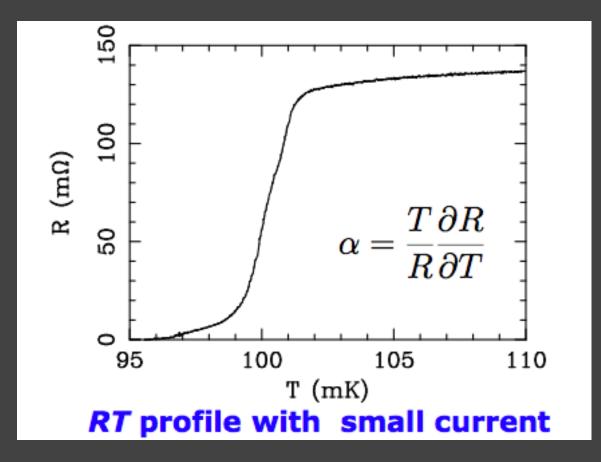
TES: TiAuTi thickness: 20/50/5 nm size: 146×150 μm<sup>2</sup>

absorber: Cu thickness: 1 μm size: 100×100 μm<sup>2</sup>





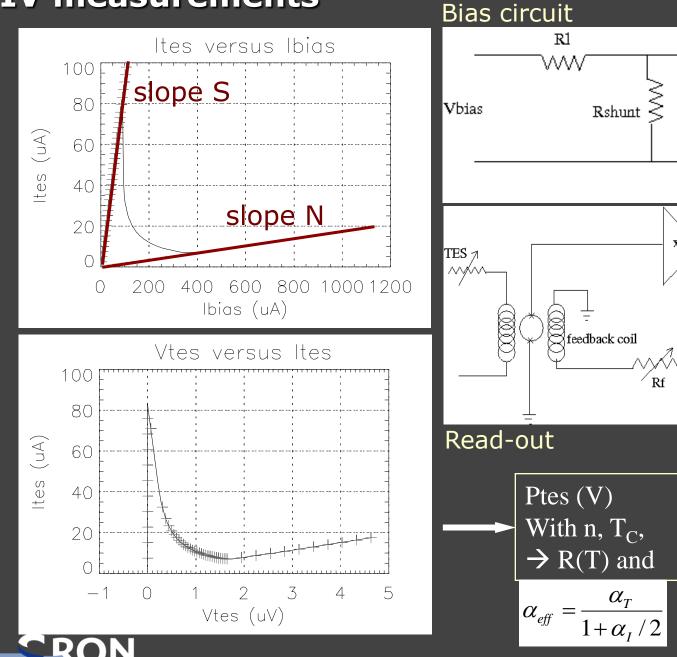
#### **RT** measurements

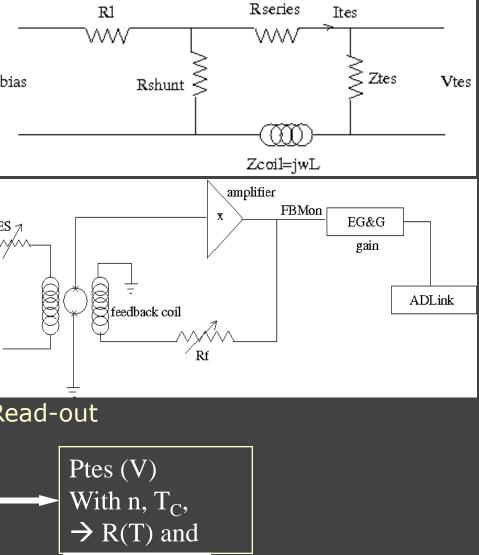


- Ti/Au bilayer with a Cu absorber
- $T_C = 100 \text{ mK}$
- $R_n = 143 \text{ m}\Omega$

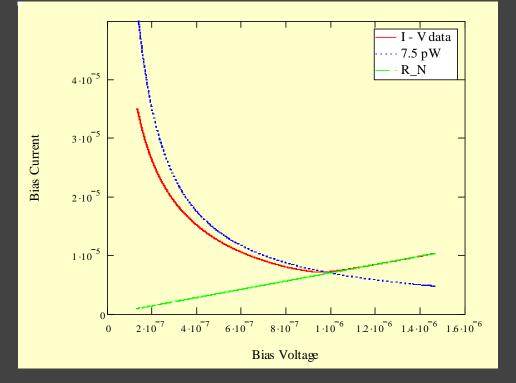


#### **IV** measurements

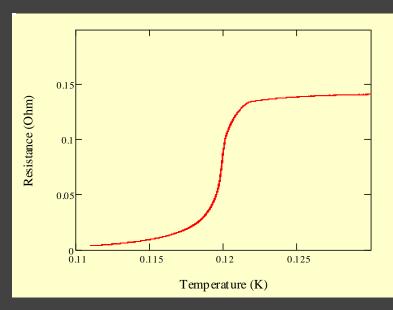




#### I – V Analysis



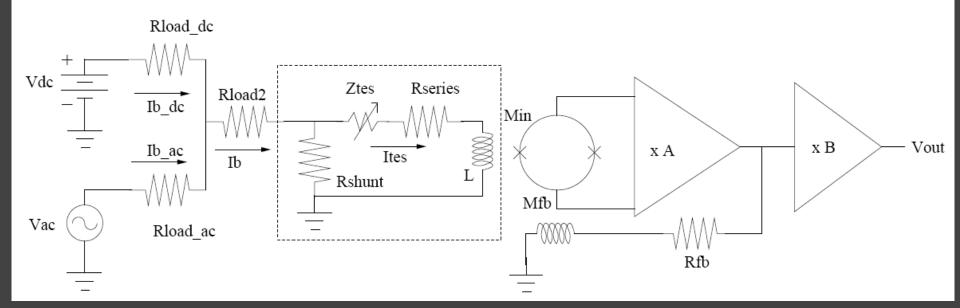
With knowledge of n (from P (T\_bath) measurements, and  $T_C$  (From R(T)) we can derive the R(T) from I – V, which is not equal to the R(T) obtained by scanning in T with a constant measurement current



 $\alpha_{eff} = \frac{\alpha_T}{1 + \alpha_I / 2}$ 



#### **Complex impedance**



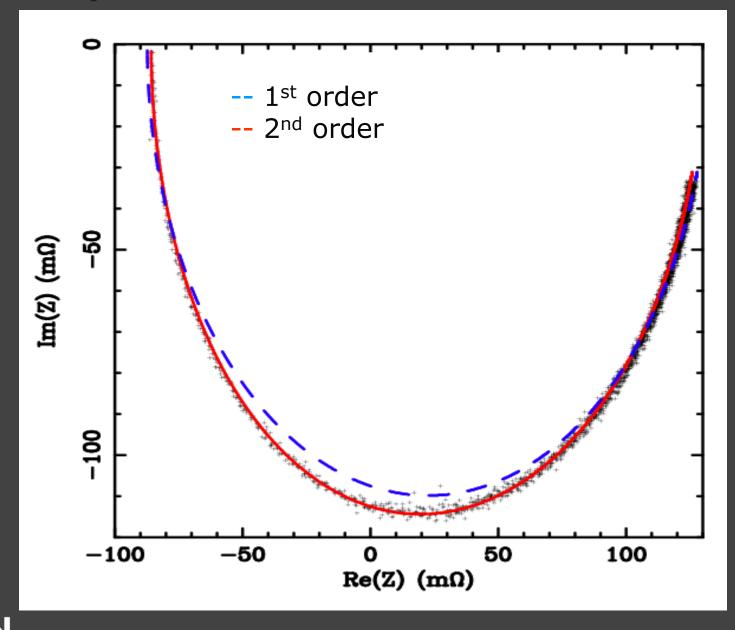
#### Bias scheme with:

$$\overline{Z}_{TES}(j\omega) = \frac{V_{AC}(j\omega)}{(R_{loadAC} + R_{load2})} \cdot \frac{R_{shunt}}{\overline{I}tes(j\omega)} \overline{T}(j\omega) - \overline{Z}_{Th}(j\omega)$$
$$\overline{Z}_{Th}(j\omega) = R_{series} + R_{shunt} + jwL$$

T(jw) : transfer function of the signal lines  $\rightarrow$  determined experimentally Znormal/Zsuper gives L, then Zsuper leads to determination of T(jw)



#### **Complex impedance**

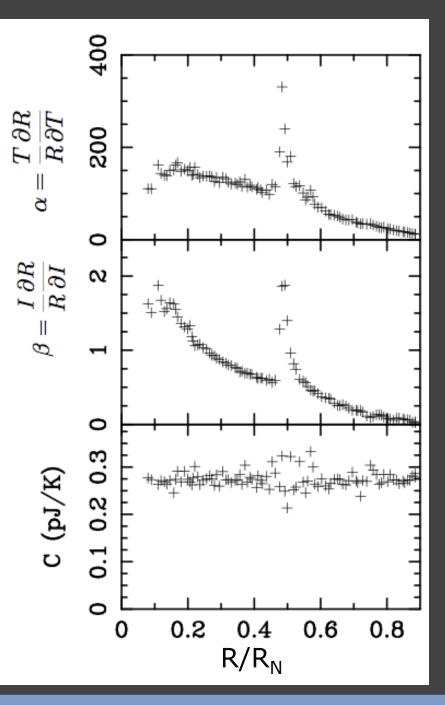


#### **Complex impedance**

2<sup>nd</sup> order due to "dangling" heat capacity with:

 $C_{D} = 0.04 \text{ pJ/K}$ 

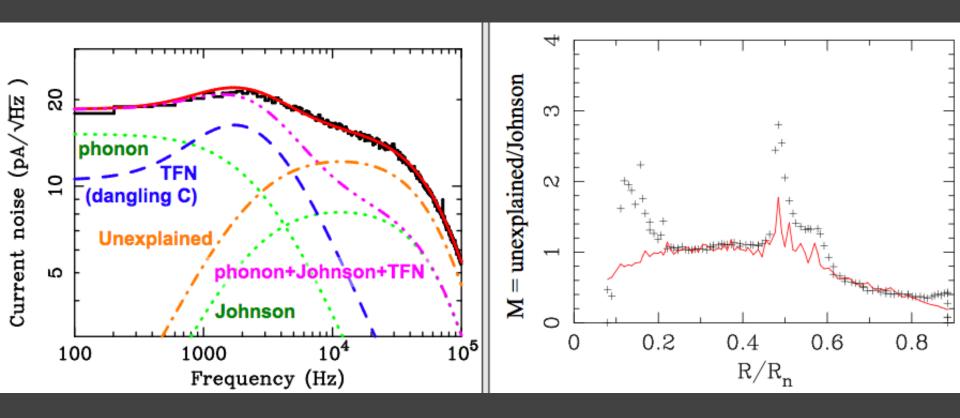
 $G_{D} = 0.4 \text{ nW/k} (\tau_{D} = 0.1 \text{ ms})$ 





### Noise (Measurement and Model)

variables from complex impedance used to fit noise spectra:



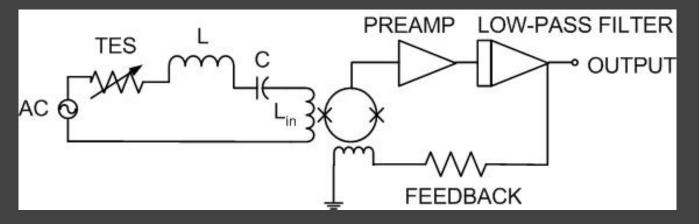


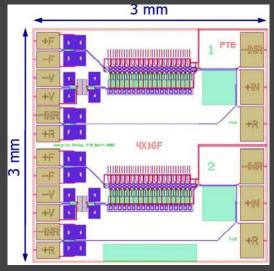
### **Read-out Electronics**

- 1) SQUID-amplifier
- 2) Multiplexing
  - 1) Introduction
  - 2) FDM
  - 3) (Baseband) Feedback
    - 1) Principle
    - 2) Characteristics
    - 3) Implementation
- 3) LC-filters



### **TES READ-OUT BY SQUID AMPLIFIER**





Typical SQUID parameters:  $L_{in} = 3 \text{ nH}$  $Ø_n = 0.22 \mu Ø_0 / \sqrt{Hz}$  $i_N = 5 \text{ pA} / \sqrt{Hz}$ Dyn.Range +/- 0.45  $10^6 \sqrt{Hz}$  Signal Characteristics:

$$i_{Johnson} = \sqrt{\frac{4kT}{R}} = 12 \text{ pA/}\sqrt{\text{Hz}}$$
$$Dyn.Range = \frac{E_{\text{max}}}{\Delta E_{rms}\sqrt{\tau}} = +/-10^{6}\sqrt{\text{Hz}}$$

Noise levels ok

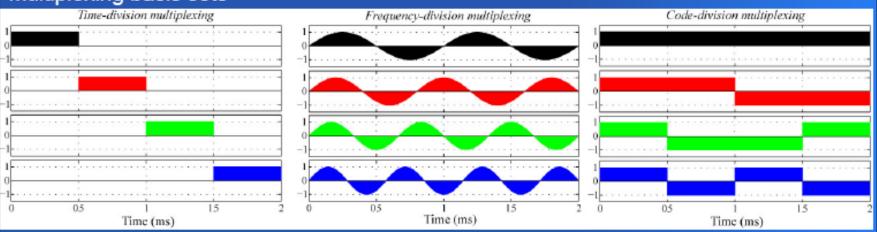
SQUID dynamic range  $\approx 6x$ too small  $\rightarrow$  feedback required for dynamic range and linearization

PTB 16-SQUID-arrays



### Multiplexing

#### Multiplexing basis sets



#### Time-division (e.g. TDMA cell phones)

 Classic SQUID multiplexer circuits that switch by turning on SQUIDs (or shunting with flux-actuated switches).

#### Frequency-division (e.g. FDMA cell phones)

Under development in SRON and Japan

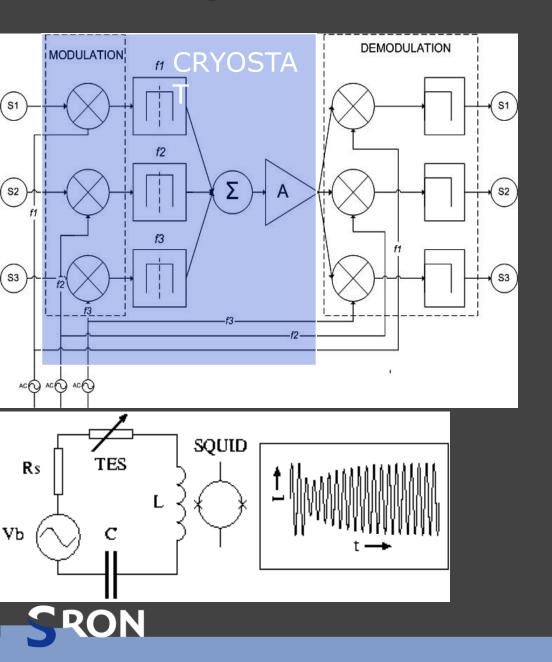
#### Code-division (e.g. CDMA cell phones)

- Uses same room-temperature electronics as TDM ("TDM Turbo")
- Only one SQUID per column
- Ultra-low-power switches modulate polarity of coupling
- Detectors dc biased
- No multiplex disadvantage



#### Courtesy to Kent Irwin

#### FREQUENCY-DOMAIN-MULTIPLEXING



1 column or row of pixelarray shown as example FDM operation:

- TESs act as AMmodulators
- TESs AC-biased at frequencies *f1, f2, f3*, ....

-Each TES equipped with LC band pass filter around carrier frequency to block wide-band noise

- Summed signal read-out by one SQUID-amplifier per column

 Demodulation by amplification and filtering

# FREQUENCY DOMAIN MULTIPLEXING Design Issues

NBF

column

SOUID

- 1) Summing topology
- 2) Chosen for current summing
- 3) Feedback required to minimize common impedance, linearize SQUID response, and increase dynamic range
- 4) LC-filter inductance set by TES stability requirements. Critical damping sets L  $\approx$  1  $\mu$ H, for R = 40 m $\Omega$  and  $\alpha_{I}$  = 1

$$L/R = \frac{1}{2}(3 + \alpha_I - 2\sqrt{2 + \alpha_I})\tau_{eff}$$

- 5) 1 10 MHz frequency range
  - > 1 MHz LC-filter capacitance large at low f
  - < 10 MHz due to SQUID back action noise
  - $(L_{in} < 0.6 \text{ nH for } k_c = 1)$ , and LC-filter losses (Q > 10.000)
- 6) Frequency spacing (> 50 kHz to keep crosstalk low)



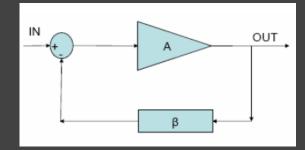
column

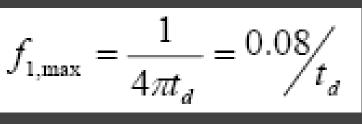
SOUID

fl

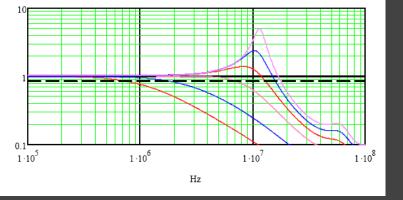
$$\omega = \frac{R}{k_c^2 L_{in}}$$

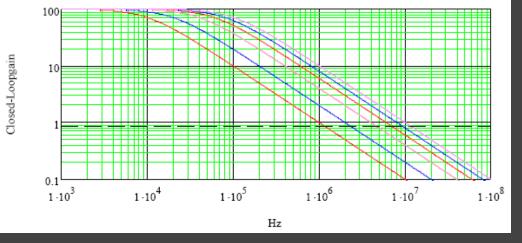
#### **Standard FLL limitations**





Delay in FLL seriously limits the available bandwidth





Closed loop response for  $\beta = 1$  and for  $\beta = 0.01$  and a 20 ns delay Resulting in a maximum stable  $f_1 = 8$  MHz. So for 6x loopgain only a bandwidth of 1.3 MHz is available



Closed-Loopgain

### **Baseband feedback**

Use the fact that:

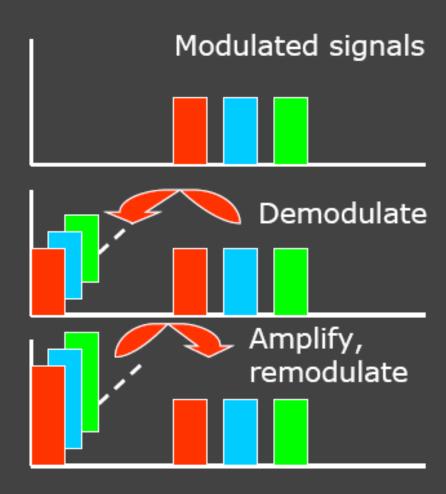
Only the envelope contains information
 The carrier is deterministic

⇒Feedback on envelope only

⇒One channel per pixel

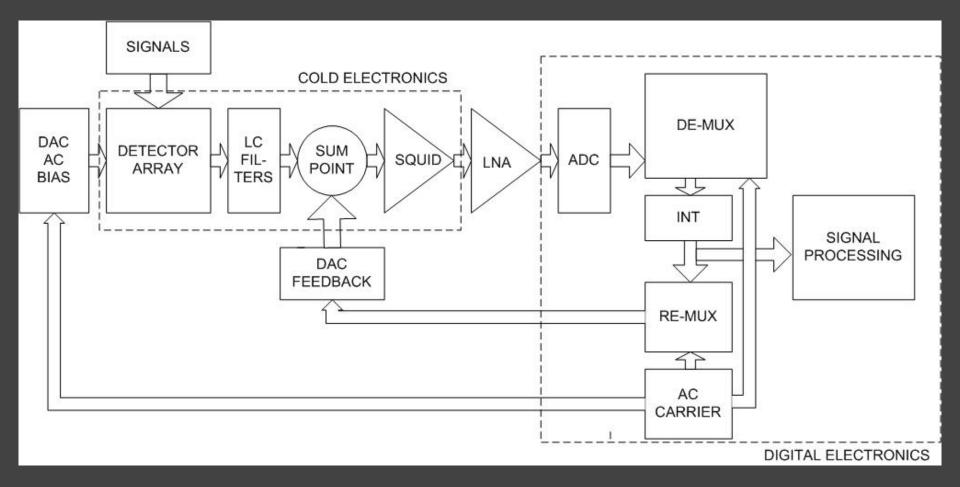
 $\Rightarrow$ Maximum GBW set by channel separation (GBW  $\approx \Delta f/6$ )

⇒Very similar to the frame rate limitation in TDM on GBW





### **Baseband feedback implementation**

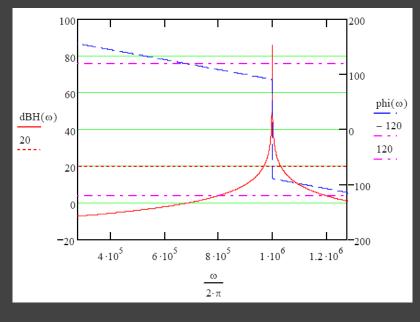


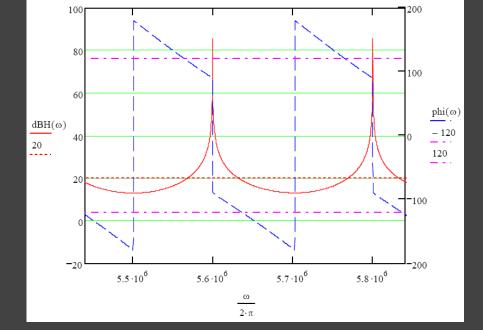


### **Baseband Feedback Filter characteristics**

$$H(\omega) = \frac{e^{-j(\omega T_d - \varphi)}}{1 + j(\omega - \omega_c)\tau}$$

The transfer function around each carrier frequency consists of an integrator, a delay term and a phase compensation of the delay



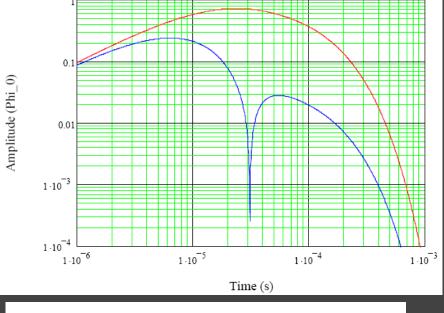


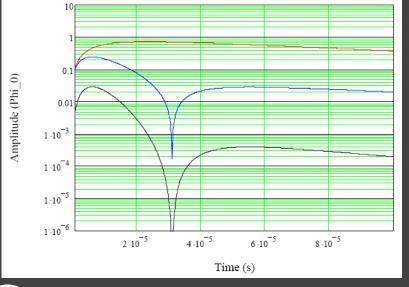
Amplitude and phase for a single Carrier (250 ns delay)

Amplitude and phase of two central carriers out of 32

For a 60° phase margin the Gain-bandwidth around each carrier is limited to about  $\Delta f/6$ , i.e. 33 kHz for 200 kHz carrier separation **CRON** 

### Simulations on error signal and 2<sup>nd</sup> harmonic





• Signal amplitude of 1  $Ø_0$  (0.2  $\mu Ø_0/\sqrt{Hz}$  noise and +/- 5  $10^6 \sqrt{Hz}$  dyn. Range)

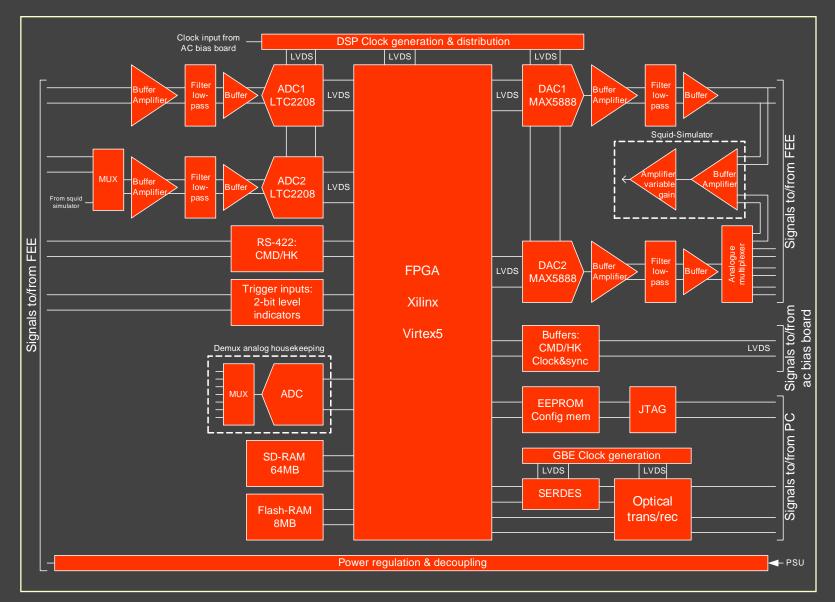
 Signal with 10 µs risetime and 100 µs falltime

• Blue error signal at SQUID input for BBFB with a GBW = 32 kHz • error signal amplitude scales with  $1/\tau_{rise}$ 

Linear time axis showing also the  $2^{nd}$  order harmonic for  $k_2/k_1 = 1$ 

The  $2^{nd}$  order contribution in this case equals 7  $10^{-3}$ 

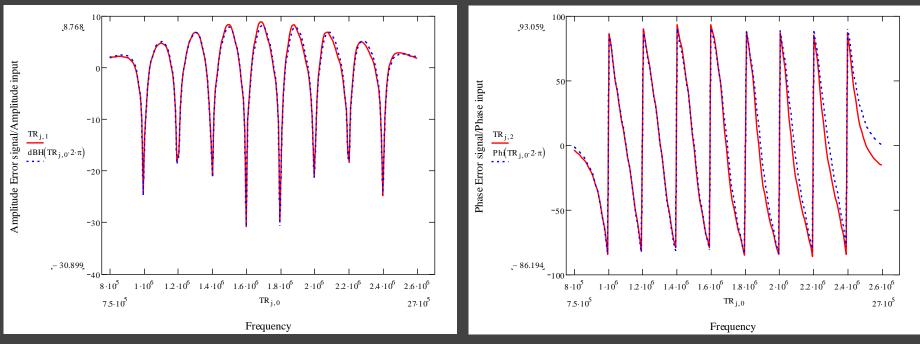
#### BaseBand Feedback Electronics board





# Amplitude and Phase (error signal/input signal) for 8 channels with BBFB

Red lines: Data from a commercial Xylinx breadboard Blue lines: Model



Amplitude: red-data blue-model Phase: red-data blue-model

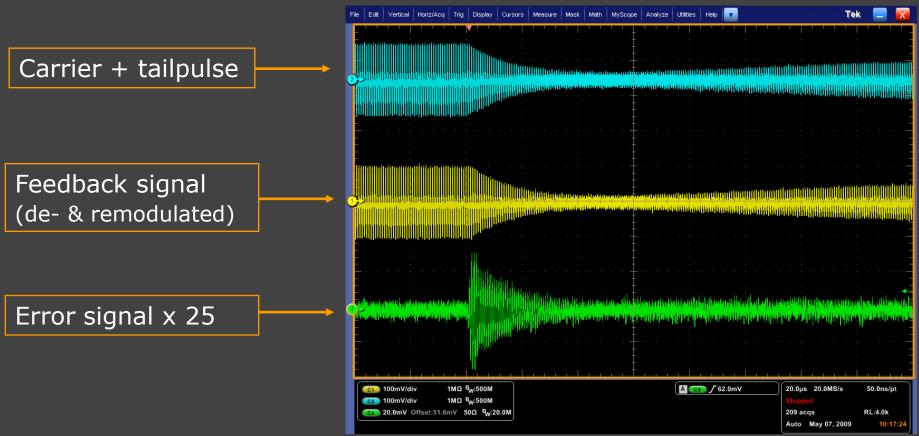
Gain-bandwidth of 35 kHz for 200 kHz spacing and 830 ns delay

FLL-gain of 2x at highest signal frequency (16 kHz)

### 2. Measurements

 TP generated by DeMux board; TES normal 367 kHz carrier generated by DeMUX board Baseband feedback by DeMux board Digitization and demodulation via DeMUX board Closure demonstrated at 367 kHz and 1 MHz

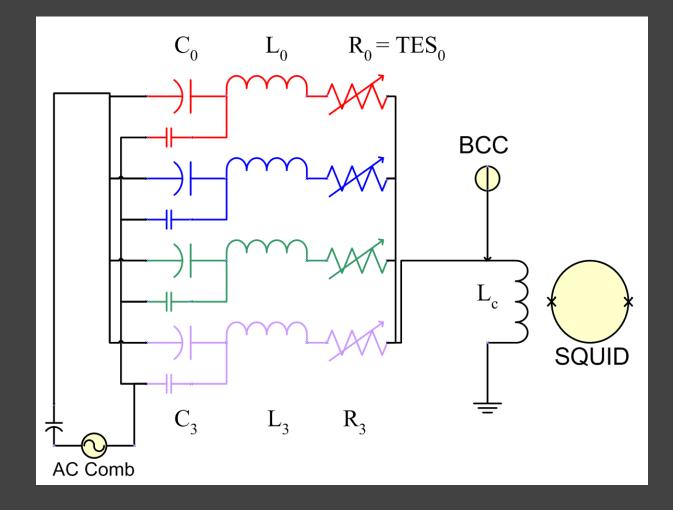
Loop gain = 18 GBW = 300 kHz





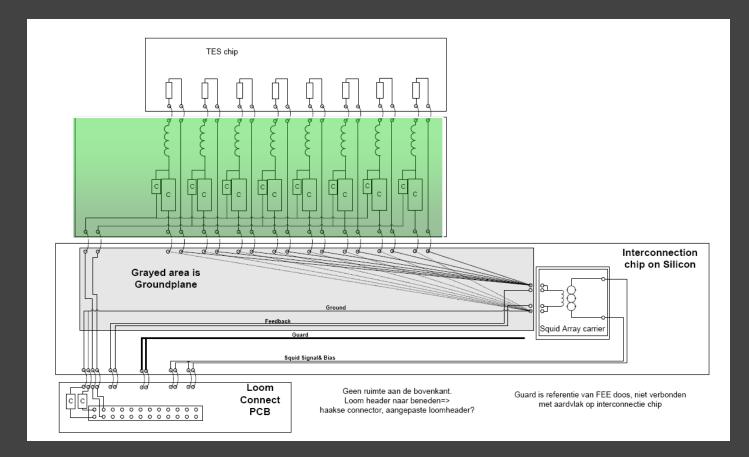
### LC-filters

### circuit & implementation





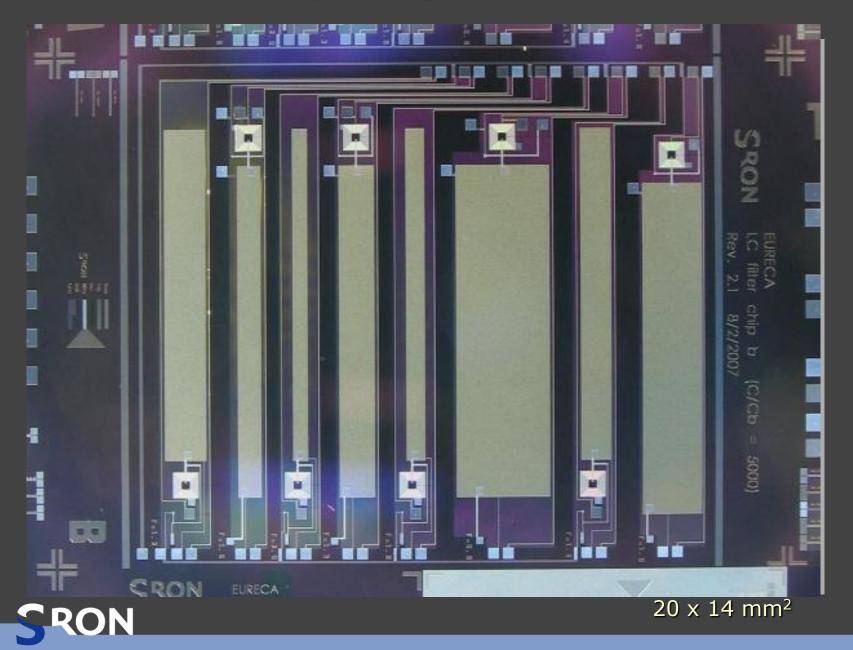
### LC-filters circuit & implementation

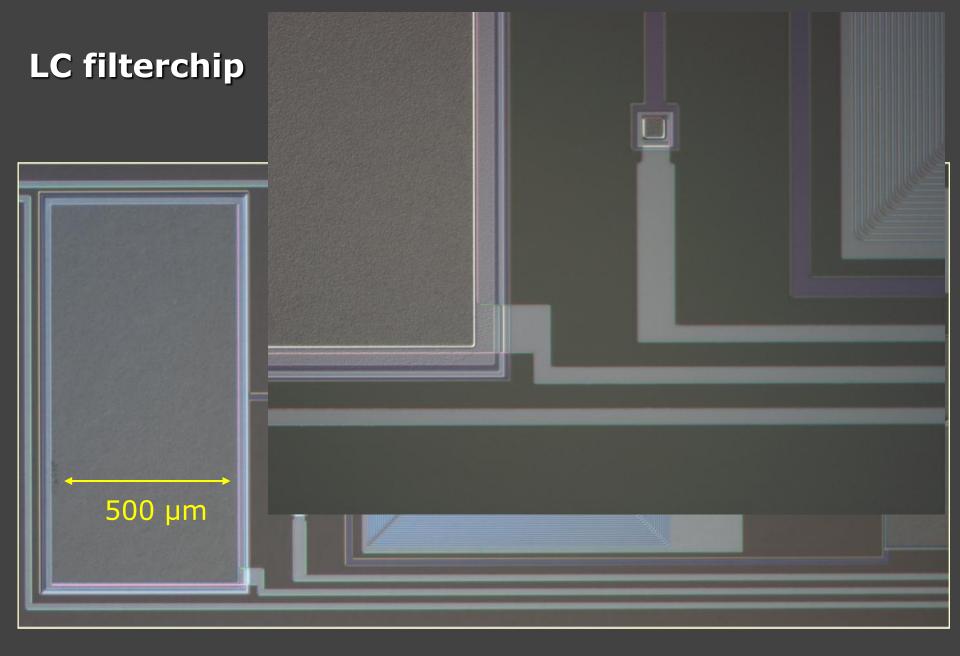


*Figure 2. Electrical scheme for the bias and signal chain of the first Eureca channel. The components for each TES chain are laid-out in parallel lanes as much as possible.* 



### 8 channel LC chip design





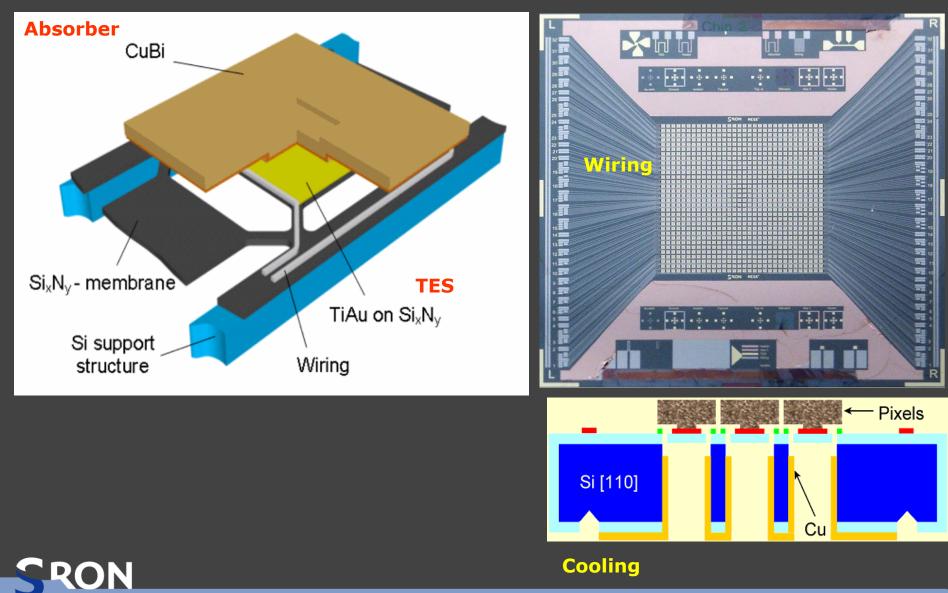


### **Contents on fabrication**

- Pixel components
  - Micro-mechanic support structure
  - TES or Transition Edge Thermometer
  - Absorber
  - Wiring
  - Pixel release
  - Cooling
- Pixel optimization:
  - Trials for steepness/excess noise
  - Avoiding strain concentrations
- Open issues
- Space qualification
- Facilities



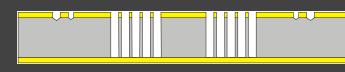
### **Calorimeter pixel components**



### **Micromechanical support structure**

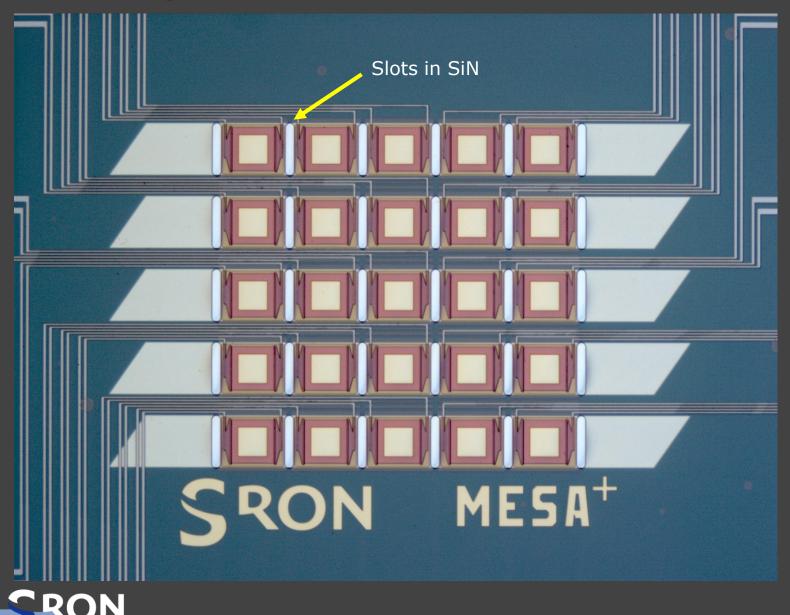
- Fabrication steps:
  - Wafer cleaning Si [110]
  - LPCVD SixNy coating @ MESA TuE
  - Vangbo alignment pattern (back side)
    - Etching SiN
    - Short KOH etch
  - Slotted pattern (back side)
    - Etching SiN
    - Long KOH etch (full wafer depth)
  - (metal processing)
  - Membrane pattern

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### **5x5** array before absorber and release



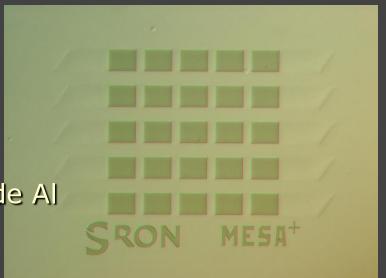
### **TES – Transition Edge Thermometer**

### Process:

- Sputtercoating of cooling layer (AI) on back side
- Evaporation of Ti/Au/Ti on front side
- Lithography of TES pattern, alignment to back side
- Wet etching
  - Ti: diluted HF
  - Au: I<sub>2</sub>/KI, rinse in Na<sub>2</sub>S<sub>2</sub>O<sub>3</sub>

Critical issues:

- Wafer handling, protection of backside Al
- Ti/Au deposition (next page)





## Ti/Au deposition

- Tc of bi-layer is very sensitive to:
  - Thicknesses
  - Interface condition
  - Purity
  - Temperature > ~100 C
  - Approach:
    - Avoid the use of "dirty" materials in the system
    - Clean vacuum
    - Automated deposition sequence with very short delay between Ti and Au (< 2 sec) and reproducible growth rate
    - Cooling of layers on membranes
    - Calibration runs before calorimeter fab.
    - Process accuracy T<sub>c</sub> +/- 15 mK

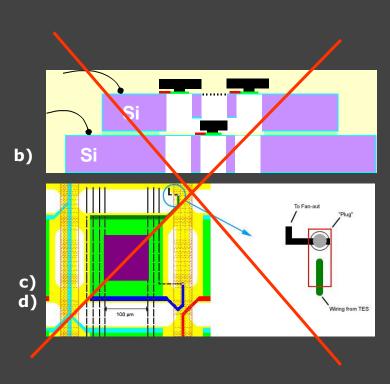


### **On-chip wiring**

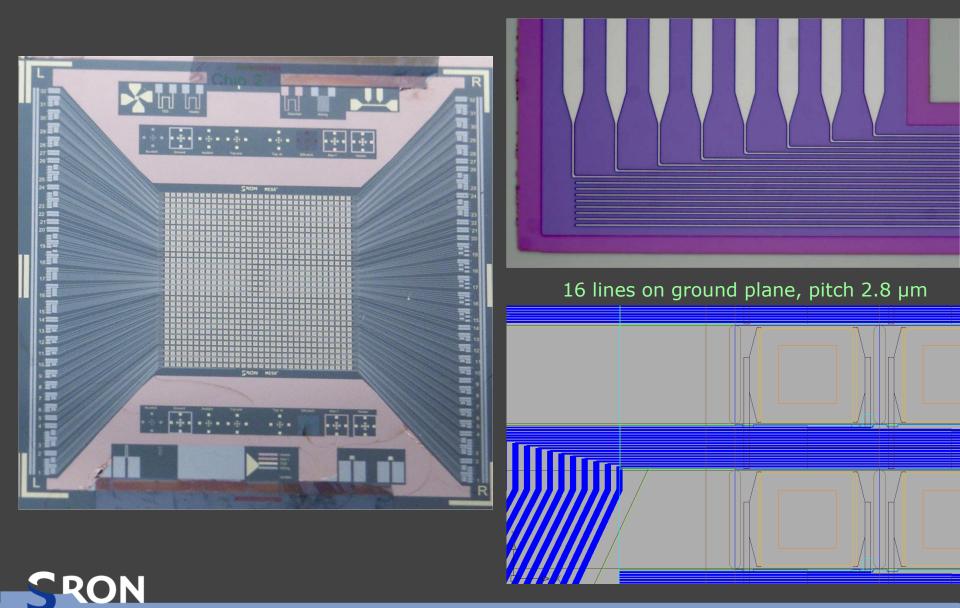
- Wiring issues become especially important for large arrays:
  - Pitch on limited space between pixel rows
  - Yield (shorts & interruptions)
  - Inductance (should be low compared to main FDM inductance)
  - Cross-talk
  - Critical current
- 4 cases were studied:
  - a) (Multi-layer) wiring on the support bars
  - b) Double wafer array
  - c) Wiring under pixel (surface micromachining)
  - d) Wiring through the wafer

Present choice: case a) seems feasible for 1 kpixel array with  $\sim$  70  $\mu m$  beams

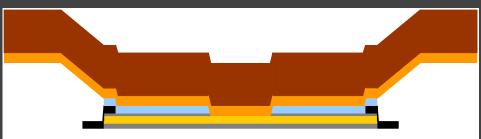




### Wiring: Prototype 32 x 32 pixel Array



### **Absorber fabrication**



Schematic sideview of pixel with overhanging absorber

#### Formation of photoresist mould



**First exposure** using an inverted mask, the exposed areas (outside the "hat" pattern) finally remain.





Third exposure is a flood exposure, Exposure dose is low to create selective development rate of the "hat" pattern with respect to the "foot" pattern (yellow).



Reversal bake, 2 min on 130 °C cross-links the exposed area while the unexposed area remains photo-active.

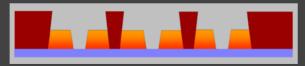


**Second exposure** of the "foot print" in proximity mode to create positive slope. The exposure dose is to generate a high development rate of the exposed (yellow) resist.



Development of the mushroom shaped mould, the development time is a parameter to adjust the height of the remaining resist which determines the distance between free-hanging absorber hat and the substrate.

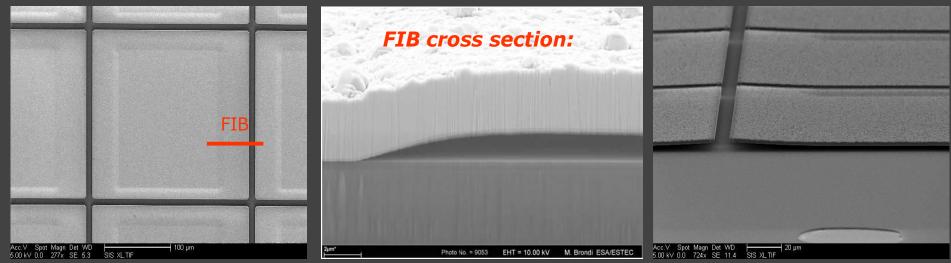
#### Array:



The negative-sloped resist forms the lateral distance between the absorbers hats.



### **Absorber fabrication**





SEM micrographs of mushroom shaped Cu/Bi absorbers.

Upper left: Top view of array on solid Si. Red line: FIB sectioning. Upper right: 70° tilted view, showing bending. Left: Process on membrane pixels.

Pixel size is  $250 \times 250 \ \mu m^2$ . Filling factor = 93%.

Present Ti/Cu/Bi thickness: 5/150/3000 nm: Good X-ray performance

### **Pixel release**

#### 

- RIE etching of SiN
- Resist removal
- Absorber pattern & deposition
- Front side resist coating
- Back side Al etch
- Lift-off (few hours)
- Rinsing
- Drying (face down in oven)

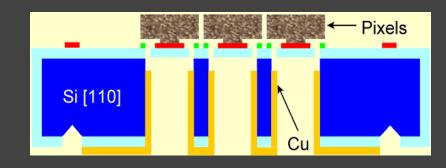
Tricky handling

- ✤ Avoid loss of Cu below Bi
- Avoid sticking of absorber to substrate





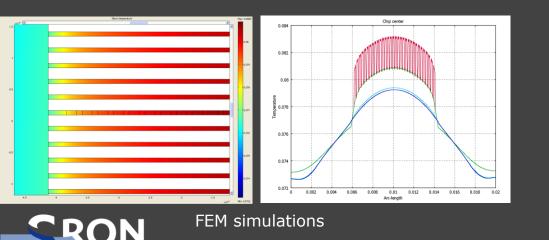
### Cooling



- Heat conduction of Si beams insufficient for bias power removal
- Cu is shadow evaporated onto sides of the beams and back side of chip
- Simulations and experiments confirm vastly improved conduction
- Thermal cross talk is reduced



Adjustable angle in evaporator



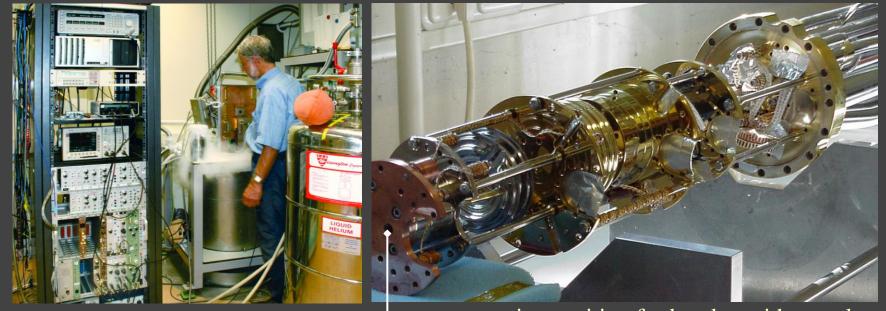


Side view on (broken) beam

### Setup's for single pixel characterization

#### Kelvinox dilution fridge

the insert



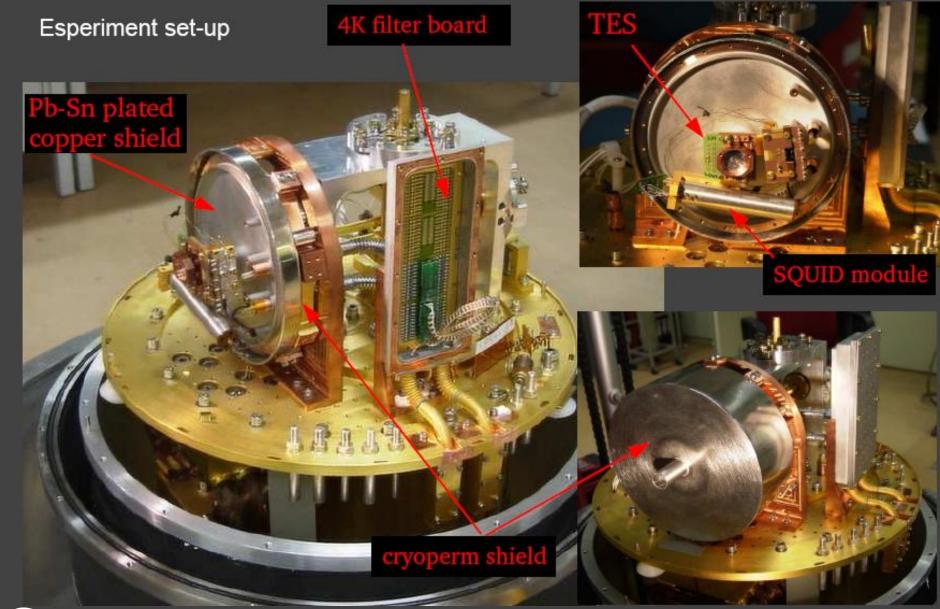
#### mounting position for bracket with samples

## For the moment FDM takes only place in ADR



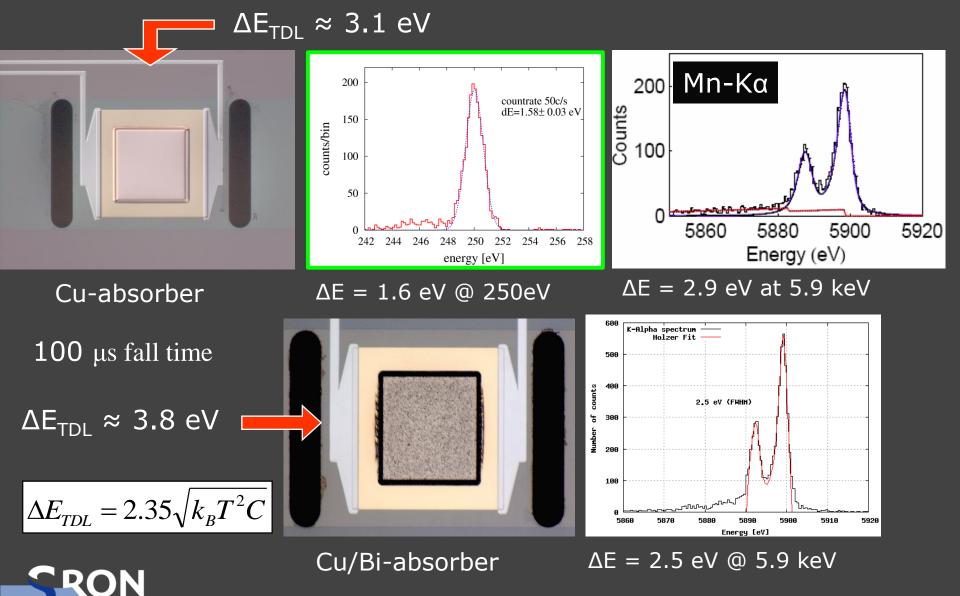


### **EMC/GROUNDING/HARNESS/FILTERING**

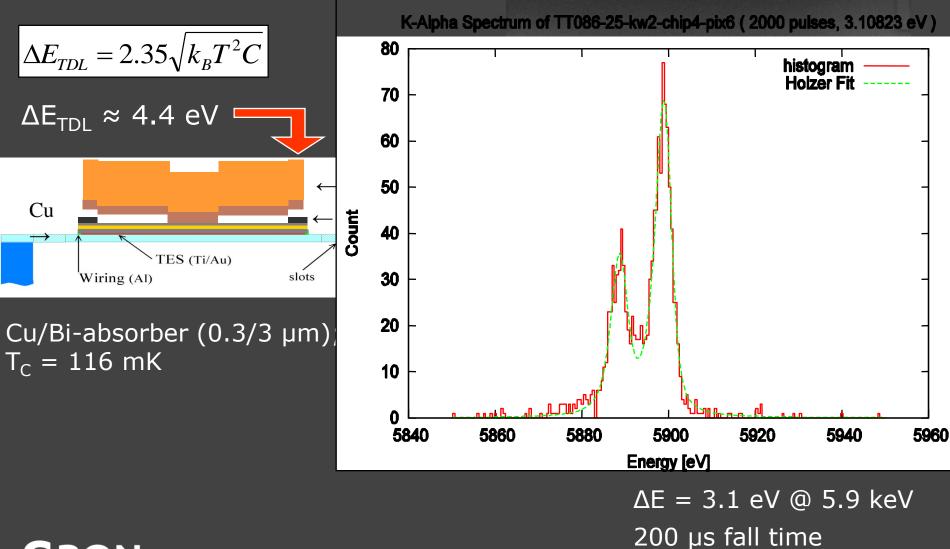




### Narrow Field Imager - TES-based Micro-Calorimeter PERFORMANCE for PIXELS from 5 x 5 arrays

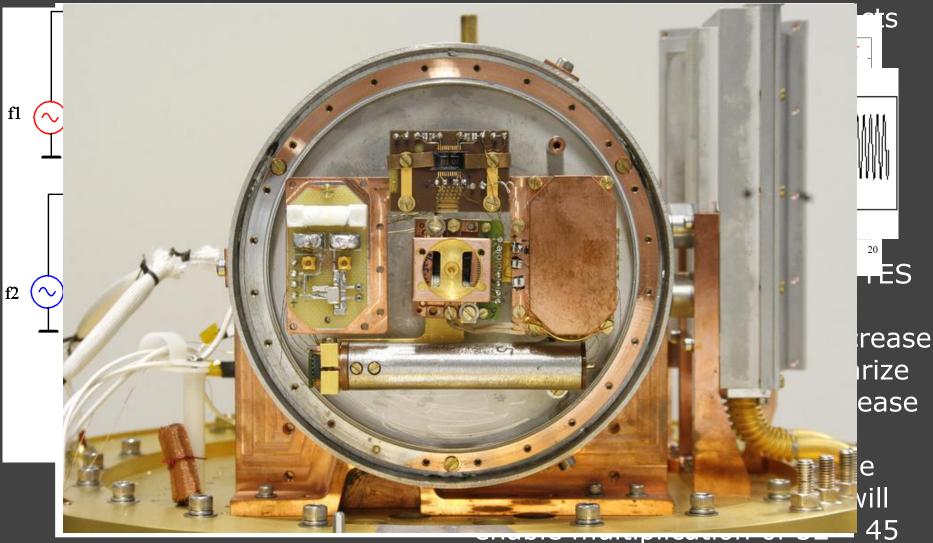


### Narrow Field Imager - TES-based Micro-Calorimeter PERFORMANCE for PIXELS from 5 x 5 arrays





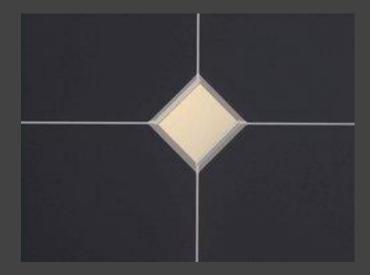
### FREQUENCY DOMAIN MULTIPLEXING CURRENT SUMMING TOPOLOGY

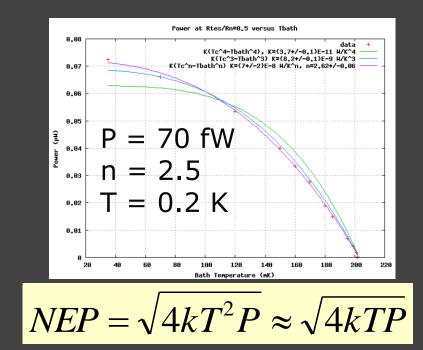


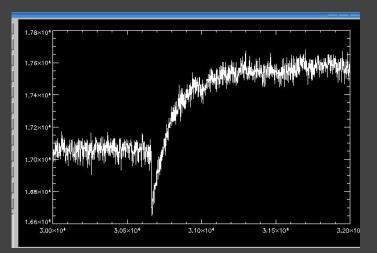


pixels/channel

# Low NEP TES for SAFARI/SPICA







 $T_{c} = 200 \text{ mK}$ 100 x 100 µm TES 4 legs of 5 µm and 1.8 mm

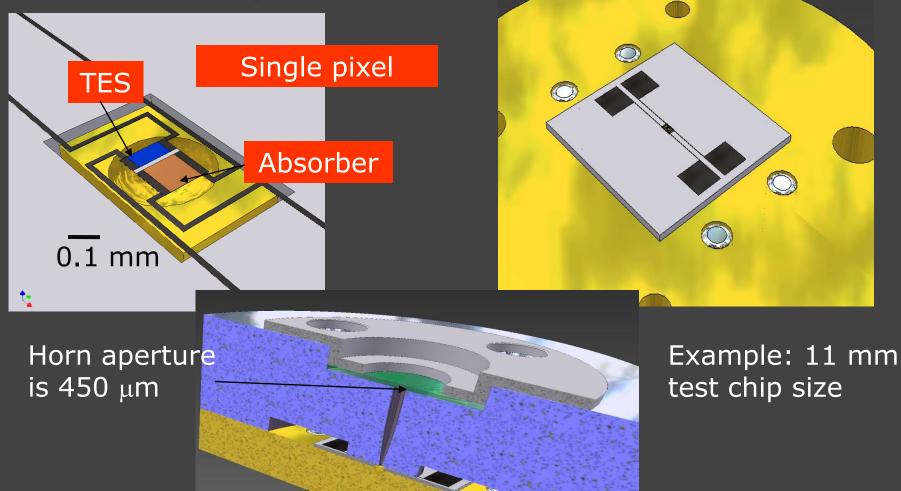
Next steps:

T  $\rightarrow$  100 mK Leg width  $\rightarrow$  2  $\mu$ m

P = 70 fW NEP =  $10^{-18}$  W/ $\sqrt{Hz}$ T<sub>eff</sub> = 0.2 ms

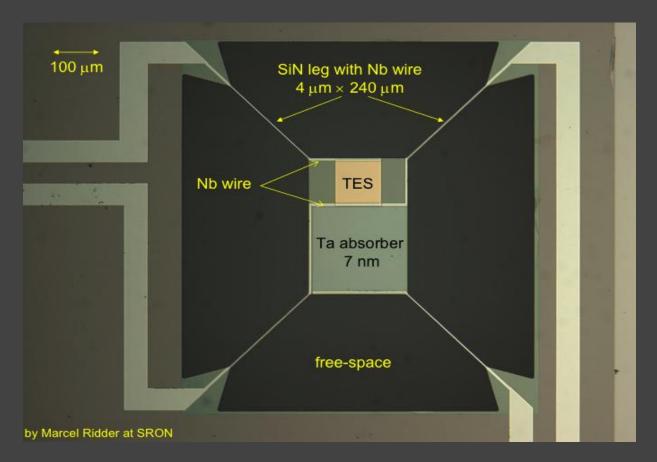
Measured

## Single optical pixel design (short wavelength channel is most difficult)





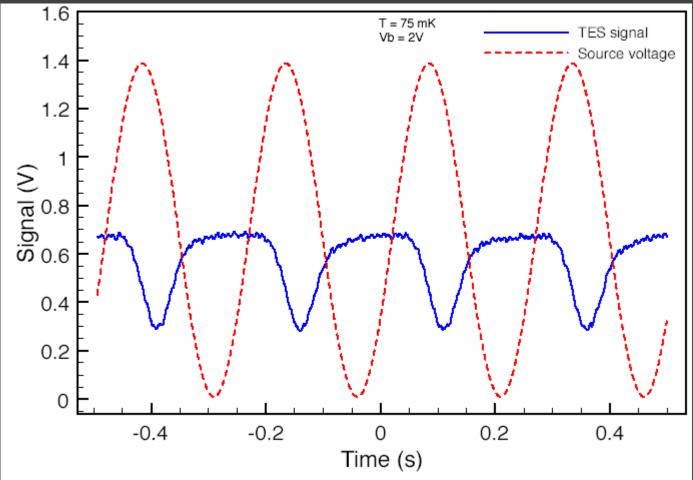
### Single pixel with optical absorber (a real picture)



Free space 400 Ohms per square absorber coupled to TES First devices fabricated and undergoing dark testing Optical testing ready to begin



### It works!!!



Absorbers fed by circular horn antennas Integrating metal backshort

